

# AIE1007: Natural Language Processing

### L13: Self-attention and Transformers

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### Recap:Attention

‣ Weighted sum of encoder hidden states: *n*  $a_t = \sum a_i^t h$ *i*=1  $a_i^t h_i^{enc} \in \mathbb{R}^h$ 



Note that  $h_1^{enc}, \ldots, h_n^{enc}$  and  $h_t^{dec}$  are hidden states from encoder and decoder RNNs.. 1  $\int$ ,  $\int$ 

- ► Encoder hidden states:  $h_1^{enc}, \ldots, h_n^{enc}$  $1 \quad \cdots \quad n$ (n: # of words in source sentence)
- Decoder hidden state at time : *h dec t*
- **EXECUTE:** Attention scores:

 $e^{t} = [g(h_1^{enc}, h_1^{dec}), \ldots, g(h_n^{enc}, h_n^{dec})] \in \mathbb{R}^n$  $1 \t t^{n} t^{n}$   $1 \t t^{n}$   $1^{n} t^{n} t^{n}$ 

**EXECUTE:** Attention distribution:

 $a^t$  = softmax $(e^t)$   $\in$   $\mathbb{R}^n$ 

Combine  $a_t$  and  $h_t^{dec}$  to predict next word *t*

### Recap:Attention



- $\bullet$ Attention addresses the "bottleneck" or fixed representation problem
- Attention learns the notion of **alignment** "Which source words are more relevant to the current target word?"

https://jalammargithub.io/visualizing-neural-machine-translation-mechanics-of-seq2seq-models-with-attention/

### a student



## Attention as a soft, averaging lookup table

We can think of **attention** as performing fuzzy lookup a in **key-value store**

**Lookup table**: a table of keys that map to values. The query matches one of the keys, returning its value.



**Attention**: The query matches to all keys softly to a weight between 0 and 1. The keys' values are multipled by the weights and summed.



(So far, we assume key = value)

Do you understand attention now?

(A)I understand the concept of attention and what it is for (B) I understand the concept + its mathematical formulations (C) I am still struggling



### Understanding attention

### Transformers

### **Attention Is All You Need**

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(Vaswani et al., 2017)



# Transformer encoder-decoder



- Transformer encoder + Transformer decoder
- First designed and experimented on NMT
- Can be viewed as <sup>a</sup> replacement for seq2seq <sup>+</sup> attention based on RNNs



### Transformer encoder-decoder



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$$
\mathbf{h}_t = f(\mathbf{h}_{t-1}, \mathbf{x}_t) \in \mathbb{R}^h
$$

### Issues with recurrent NNs

• Longer sequences can lead to vanishing gradients  $\implies$  It is hard to capture **longdistance information**



- RNNs **lack parallelizability**
	- Forward and backward passes have O(sequence length) unparallelizable operations
	- GPUs can perform a bunch of independent computations at once!
	- Inhibits training on very large datasets

RNNs / LSTMs seq2seq seq2seq + attention attention only = Transformers! Transformers have become a new building block to replace RNNs

### Transformers: roadmap



- From attention to self-attention
- From self-attention to multi-head self-attention
- Feedforward layers
- Positional encoding
- Residual connections + layer normalization
- Transformer encoder vs Transformer decoder



Reminder: we will ask you to implement Transformer encoderdecoder in A4!

### Attention in a general form

- Assume that we have a set of values  $\mathbf{v}_1, ..., \mathbf{v}_n \in \mathbb{R}^{d_v}$  and a <mark>query</mark> vector  $\mathbf{q} \in \mathbb{R}^{d_q}$
- Attention always involves the following steps:
	- Computing the attention scores  $e = g(q, v_i)$  2 R<sup>n</sup>
	- Taking softmax to get **attention distribution** :
		- ↵= softmax(**e**) *2* R*<sup>n</sup>*
	- Using attention distribution to take **weighted sum** of values: •

$$
a = \sum_{i=1}^{R} \sqrt{v_i} \cdot 2R
$$

 $Q$ *d*<sub>*v*</sub>

### Attention in a general form

- $\bullet$  A more general form: use a set of keys and values  $(\mathbf{k}_1, \mathbf{v}_1), ..., (\mathbf{k}_n, \mathbf{v}_n), \mathbf{k}_i \in \mathbb{R}^{d_k}, \mathbf{v}_i \in \mathbb{R}^{d_v}$ keys are used to compute the attention scores and values are used to compute the output vector
- Attention always involves the following steps:
	- Computing the attention scores  $e = g(q, k_i)$  2 R<sup>n</sup>
	- Taking softmax to get **attention distribution** :

$$
\Box = \text{softmax}(\mathbf{e}) \ 2 \ \mathsf{R}^n
$$

Using attention distribution to take **weighted sum** of values: •

$$
a = \sum_{i=1}^{\infty} \sqrt{v_i} \cdot 2 \cdot R^{d_v}
$$

- In NMT, query = decoder hidden state, keys = values = encoder hidden states
- Self-attention <sup>=</sup> attention from the sequence to **itself**
- Self-attention: let's use each word in a sequence as the query, and all the other words in the sequence as keys and values.





A self-attention layer maps a sequence of input vectors  $\mathbf{x}_1, ..., \mathbf{x}_n \in \mathbb{R}^{d_1}$  to a sequence of *n* vectors:  $\mathbf{h}_1, ..., \mathbf{h}_n \in \mathbb{R}^{d_2}$ 

• The same abstraction as RNNs - used as a drop-in replacement for an RNN layer  $\mathbf{h}_t = g(\mathbf{W}\mathbf{h}_{t-1} + \mathbf{U}\mathbf{x}_t + \mathbf{b}) \in \mathbb{R}^h$ 



$$
\mathbf{k}_{i} = \mathbf{W}^{(k)}\mathbf{x}_{i}, \quad \mathbf{v}_{i} = \mathbf{W}^{(v)}\mathbf{x}_{i},
$$
\n
$$
\left(\frac{\exp(\mathbf{q}_{i} \cdot \mathbf{k}_{j}/\sqrt{d})}{\sum_{j'=1}^{n} \exp(\mathbf{q}_{i} \cdot \mathbf{k}_{j'}/\sqrt{d})}\mathbf{v}_{j}\right)
$$

Step #1: Transform each input vector into three vectors: query, key, and value vectors

Note that we use row vectors here; It is also common to write  $\mathbf{q}_i = \mathbf{W} \mathcal{Q} \mathbf{x}_i \in \mathbb{R}^{d_q}$ for  $\mathbf{x}_i$  = a column vector

$$
\mathbf{q}_{i} = \mathbf{x}_{i} \mathbf{W}^{Q} \in \mathbb{R}^{d_{q}} \qquad \mathbf{k}_{i} = \mathbf{x}_{i} \mathbf{W}^{K} \in \mathbb{R}^{d_{k}} \qquad \mathbf{v}_{i} = \mathbf{x}_{i} \mathbf{W}^{V} \in \mathbb{R}^{d_{v}}
$$

$$
\mathbf{W}^{Q} \in \mathbb{R}^{d_{1} \times d_{q}} \qquad \mathbf{W}^{K} \in \mathbb{R}^{d_{1} \times d_{k}} \qquad \mathbf{W}^{V} \in \mathbb{R}^{d_{1} \times d_{v}}
$$



Step #2: Compute pairwise similarities between keys and queries; normalize with softmax For each **q***<sup>i</sup>* , compute attention scores and attention distribution:

aka. "scaled dot product" It must be  $d_q = d_k$  in this case

Keys

Q. Why scaled dot product? Values

Score To avoid the dot product to become too large 1 for larger  $d_k$ ; scaling the dot product by  $\sqrt{d_k}$ 

https://jalammar.github.io/illustrated-transformer/

$$
d_{i,j} = \text{softmax}(\frac{\mathbf{q}_i \cdot \mathbf{k}_j}{d_k})
$$

is easier for optimization





**Thinking Machines** dding  $X<sub>1</sub>$ X2  $q<sub>2</sub>$  $q_1$ es  $k<sub>2</sub>$  $k_1$ S  $V<sub>2</sub>$  $V<sub>1</sub>$  $q_1$  •  $k_1 = 112$  $q_1 \cdot k_2 = 96$ by 8 (  $\sqrt{d_k}$  )  $12$ 14 0.88  $0.12$ ax ax  $V<sub>2</sub>$  $V<sub>1</sub>$ *h*<sup>1</sup> *h*<sup>2</sup>

Input Embedding What would be the output vector for the word "Thinking" approximately? Queries Keys (a)  $0.5v_1 + 0.5v_2$ Values (b)  $0.54$ **v**<sub>1</sub> +  $0.46$ **v**<sub>2</sub> Score (c)  $0.88v_1 + 0.12v_2$ Divide by 8 ( $\sqrt{d_k}$ ) Softmax (d)  $0.12v_1 + 0.88v_2$ Softmax  $\mathsf{X}$ Value (c) is correct.

Sum



### Self-attention



### Self-attention: matrix notations

 $X$  2 R<sup>n→ $d_1$ </sup> (n = input length)

 $Q = XW^Q$  $K = XW^K$   $V = XW^V$ 

*W*<sup>Q</sup> 2 R<sup>*d*<sub>1→*dq*</sub></sup>, *W<sup>K</sup>* 2 R<sup>*d*<sub>1→*dk*</sub></sup>, *W<sup>V</sup> 2 R<sup><i>d*<sub>1→</sub>*d*<sub>*v*</sub></sub></sup>





Q: What is this softmax operation?

### Multi-head attention

•

"The Beast with Many Heads"

It is better to use multiple attention functions instead of one! • Each attention function ("head") can focus on different positions.





Finally, we just concatenate all the heads and apply an output projection matrix.

$$
\text{MultiHead}(Q, K, V) = \text{Concat}(\text{head}_1, ..., \text{head}_h)W^O
$$
\n
$$
\text{head}_i = \text{Attention}(XW^Q, XW^K, XW^V)
$$



### Multi-head attention

"The Beast with Many Heads"

- In practice, we use <sup>a</sup> *reduced* dimension for each head.  $W_i^Q$  2 R<sup> $a_1 \rightarrow a_q$ </sup>,  $W_i^R$  2 R $a_1 \rightarrow a_k$ ,  $W_i^V$  2 R  $d_1 \rightarrow d_q$ ,  $W_i^{\prime\prime}$  2 R<sup> $a_1 \rightarrow a_k$ </sup>,  $W_i$  $K \rightarrow R^{d_1 \rightarrow d_k}$  *M*<sup>V</sup>  $\rightarrow R^{d_1 \rightarrow d_k}$  $d_q = d_k = d_v = d/m$  *d* = hidden size, *m* = # of heads  $W^O$  *2* R<sup>*d*<sub>→ $d$ 2</sub> If we stack multiple layers, usually  $d_1 = d_2 = d$ </sup>
- The total computational cost is similar to that of single-head attention with full dimensionality.
- 
- 



### What does multi-head attention learn?





https://github.com/jessevig/bertviz

### Missing piece: positional encoding

- Unlike RNNs, self-attention doesn't build in order information, we need to encode the order of the sentence in our keys, queries, and values
- Solution: Add "positional encoding" to the input embeddings:  $\mathbf{p}_i \in \mathbb{R}^d$  for  $i = 1, 2, ..., n$

 $\mathbf{x}_i$   $\mathbf{x}_i + \mathbf{p}_i$ 

• **Sinusoidal position encoding**: sine and cosine functions of different frequencies:

$$
p_{i} = \begin{pmatrix} \sin(i/10000^{2*1/d}) \\ \cos(i/10000^{2*1/d}) \\ \vdots \\ \sin(i/10000^{2*2/d}) \\ \cos(i/10000^{2*2/d}) \end{pmatrix}
$$



- **Pros**: Periodicity + can extrapolate to longer sequences
- **Cons**: Not learnable

Index in the sequence

### Missing piece: positional encoding

- **Learned absolute position encoding:** let all **p***<sup>i</sup>* be learnable parameters
	- $P \in \mathbb{R}^{d \times L}$  for  $L = \max$  sequence length
	- **Pros**: each position gets to be learned to fit the data
	- **Cons**: can't extrapolate to indices outside of max sequence length *L*
	- Most systems use this!

### **Self-Attention with Relative Position Representations**

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### ROFORMER: ENHANCED TRANSFORMER WITH ROTARY **POSITION EMBEDDING**

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# Adding nonlinearities

- There are no elementwise nonlinearities in self-attention; stacking more self-attention layers just re-averages value vectors
- Simple fix: add a feed-forward network to post-process each output vector

 $FFN(x_i) = ReLU(x_iW_1 + b_1)W_2 + b_2$  $W_1$  2  $R^{d \rightarrow d_f}$ f,  $b_1$  2  $R^{d_f}$ **W**<sup>2</sup> *2* R*<sup>d</sup><sup>f</sup> <sup>f</sup>* ⇥*<sup>d</sup> ,* **b**<sup>2</sup> *2* R*<sup>d</sup>*

In practice, they use  $d_f = 4d$ 



Which of the following statements is correct?

(b) is correct.



- (a) Transformers have less operations compared to LSTMs
- (b) Transformers are easier to parallelize compared to LSTMs
- (c) Transformers have less parameters compared to LSTMs
- (d) Transformers are better at capturing positional information than LSTMs

### Transformers vs LSTMs

## Transformer encoder: let's put things together



From the bottom to the top:

- Input embedding
- Positional encoding
- <sup>A</sup> stack of Transformer encoder layers

- Multi-head attention layer
- Feed-forward layer
- Transformer encoder is a stack of *N* layers, which
	-

### $\mathbf{h}_1, \ldots, \mathbf{h}_n \in \mathbb{R}^{d_1}$  **h**<sub>1</sub>, ..., **h**<sub>*n*</sub>  $\in \mathbb{R}$  $d_2$

consists of two sub-layers:

$$
\mathbf{x}_1, ..., \mathbf{x}_n \in \mathbb{R}^{d_1}
$$

### Residual connection & layer normalization Add & Norm: LayerNorm $(x + Sublayer(x))$

**Residual connections** (He et al., 2016) Instead of  $X^{(i)} = \text{Layer}(X^{(i-1)})$  (*i* represents the layer)

$$
X^{(i-1)} \longrightarrow \text{Layer} \longrightarrow X^{(i)}
$$

We let  $X^{(i)} = X^{(i-1)} + \text{Layer}(X^{(i-1)})$ , so we only need to learn "the residual" from the previous layer

$$
X^{(i-1)} \longrightarrow \text{Layer} \longrightarrow X^{(i)}
$$

Gradient through the residual connection is 1 - good for propagating information through layers

### Residual connection & layer normalization Add & Norm: LayerNorm $(x + Sublayer(x))$

**Layer normalization** (Ba et al., 2016) helps train model faster

Idea: normalize the hidden vector values to unit mean and stand deviation within each layer

**[advanced]**

$$
y = \frac{x - \mathrm{E}[x]}{\sqrt{\mathrm{Var}[x] + \epsilon}} * \gamma + \beta
$$

*γ*, *β* ∈  $\mathbb{R}^d$  are learnable parameters

### Transformer decoder

Transformer decoder is a stack of *N* layers, which consists of three sub-layers:

- Masked multi-head attention
- Multi-head cross-attention
- Feed-forward layer
- (W/ Add & Norm between sub-layers)

From the bottom to the top: Output embedding Positional encoding A stack of Transformer decoder layers • Linear + softmax • • •

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